Description:

The USB interface board provides a means of connecting a computer to the NCE cab bus. While primarily designed to provide a computer interface to the Power Cab program track, it can additionally be used with any NCE system to run trains, control signals, turnouts and Program on the Main (OPs mode programming).

When used with the Power Cab the USB board cab bus address must be 3. When the appropriate shunts are installed to configure the USB board for use with a Power Cab the address is automatically forced to cab bus address 3. When configured for a different NCE system the cab bus address can be changed via a command (binary command 0xB1) through the USB port.

Optical isolation is provided to prevent "sneak path" short circuits when connected to a computer.

You may use as many USB interface boards as you wish, up to the limit of available cab addresses on your DCC system. Each USB board draws only 45mA from the Cab Bus power.

USB Driver Installation:

We recommend having the USB driver for your operating system available **before** connecting the USB interface board to your computer system. Due to the constant change of drivers for computer products we do not provide a disc with drivers for your computer. We do keep our website up to date with the latest drivers and driver installation manual. You can download these from the NCE website (www.ncedcc.com/usb_drivers).

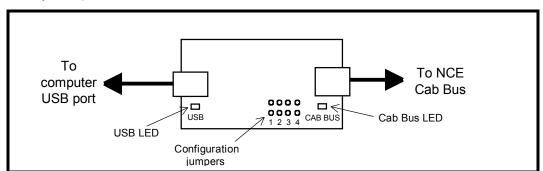
Note: If installing on a Win XP or Vista machine you can also let the Windows driver installation program search the Internet for the proper driver.

Mechanical Installation:

The USB interface has 4 mounting holes that can be used to mount it to a convenient place on your layout. We recommend using #4 x 3/4" round head wood screws with #4 flat washers. <u>Do not over tighten the screws</u>. Lightly snug the screws up just enough to keep the circuit board in place without bending it. Bending the circuit board can fracture the fragile ceramic electronic components.

Electrical Connections:

The diagram below illustrates the wiring of the USB interface between your computer and DCC system. The computer connection is via Type A to Type B USB cable. Connection to the NCE Cab Bus is via the supplied modular cable. This product will only work with NCE DCC system products.



Configuration jumpers for USB board

JP1 off = 9600 baud JP1 on = 19200 baud

Jumpers matching the system/version table below MUST be installed for proper operation. Some commands are "massaged" by the USB board to accommodate bugs in different devices so the board needs to know what system it is connected to by reading the jumpers.

Install the included shunts (jumpers) to match your DCC system.

System and Version (as read on cab LCD)	JP2	JP3	JP4	Version reported to computer by 0xaa command
Power Cab v1.28c	-	-	-	6.3.0
SB3 v1.28b	-	-	ON	6.3.1
PH Pro 2007	-	ON	-	6.3.2
All Sys ¹	-	ON	ON	6.3.3
Future Versions				
Power Cab	ON	-	-	6.3.4
SB3	ON	_	ON	6.3.5
unused	ON	ON	-	6.3.6
unused	ON	ON	ON	6.3.7

Notes:

- 1) "All Sys" means the USB board makes no distinction between what version system you are using and passes all commands from the computer to the USB board
- 2) The third byte returned by the version command (0xaa) is the "bit-reversed" status of jumpers 2,3 and 4 (see table above).

Technical things you should know:

- The USB board forces the cab bus address to 3 when used with a PowerCab.
- The USB board cab bus address and baud rate is initialized only at power up.
 All board power comes from the cab bus connection so the board must be power cycled via unplugging from the cab bus if the address is changed.
- Cab bus addresses for the SB3 are limited to a range of 2 through 5.
- Multiple USB boards may be used with a system (except Power Cab) for control by multiple computers. Each USB board must have a different cab address ranging from 2 to 63 on Power Pro systems and 2-5 on SB3 systems.

Beyond this point is technical stuff you probably don't need to read unless you are writing your own software

Commands supported by PowerCab-1.28 (no jumpers)

Hex	Bytes	Description
0x80	1 bytes	NOP just returns '!'
0x8C	1 bytes	Returns !,CR,LF
0x9C	2 bytes	Execute route macro
0x9E	1 bytes	Enter program track mode
0x9F	1 bytes	Exit program track mode
0xA0	4 bytes	Write a CV in paged mode
0xA1	3 bytes	Read a CV in paged mode
0xA2	5 bytes	Locomotive control command
0xA6	3 bytes	Write in register mode
0xA7	2 bytes	Read in register mode
0xA8	4 bytes	Write in direct mode
0xA9	3 bytes	Read in direct mode
0xAA	1 bytes	Return C/S software version (USB board = $6.3.x$ - see table for value of x)
0xAD	5 bytes	Accy/signal/macro commands (NOTE: accy/sig addresses limited to range of 1-250)
0xAE	6 bytes	Locomotive OPs program byte
0xAF	6 bytes	Accy/Signal OPs program byte (NOTE: accy/sig addresses limited to range of 1-250)
0xB0	5 bytes	reserved - factory test

Notes: jumpers MUST be installed to match

Commands supported by SB3-1.28 - JP4 only

Hex Bytes	Description
0x80 1 bytes	NOP just returns '!'
0x8C 1 bytes	Return !,CR,LF
0x9C 2 bytes	Execute route macro
0xA2 5 bytes	Locomotive control command
0xAA 1 bytes	Return C/S software version
0xAD 5 bytes	Accy/signal/macro commands (NOTE: accy/sig addresses limited to range of 1-250)
0xAE 6 bytes	Locomotive OPs program byte
0xAF 6 bytes	Accy/Signal OPs program byte (NOTE: accy/sig addresses limited to range of 1-250)
0xB0 5 bytes	reserved - factory test
0xB1 2 bytes	Set cab address of USB device

Commands supported by Power Pro 2007 version - JP3 only

Hex Bytes	Description
0x80 1 bytes	NOP just returns '!'
0x8C 1 bytes	Returns !,CR,LF
0x9C 2 bytes	Execute route macro
0xA2 5 bytes	Locomotive control command
0xAA 1 bytes	Return C/S software version
0xAD 5 bytes	Accy/signal/macro commands (no limit on accy/sig addresses)
0xAE 6 bytes	not supported due to bug in command station software
0xAF 6 bytes	not supported due to bug in command station software
0xB0 5 bytes	reserved - factory test
0xB1 2 bytes	Set cab bus address of this USB device (this command only works internally to the USB interface it does not get to the command station)

Commands supported by ALLSYS - JP3 and JP4

Hex Bytes	Description
0x80 1 bytes	NOP just returns '!'
0x8C 1 bytes	Returns !,CR,LF
0x9C 2 bytes	Execute route macro
0x9E 1 bytes	Enter program track mode
0x9F 1 bytes	Exit program track mode
0xA0 4 bytes	Write a CV in paged mode
0xA1 3 bytes	Read a CV in paged mode
0xA2 5 bytes	Locomotive control command
0xA6 3 bytes	Write in register mode
0xA7 2 bytes	Read in register mode
0xA8 4 bytes	Write in direct mode
0xA9 3 bytes	Read in direct mode
0xAA 1 bytes	Return C/S software version
0xAD 5 bytes	Accy/signal/macro commands
0xAE 6 bytes	Locomotive OPs program byte
0xAF 6 bytes	Accy/Signal OPs program byte
0xB0 5 bytes	reserved - factory test
0xB1 2 bytes	Set cab bus address of this USB device (this command only works internally to the USB interface it does not get to the command station)

A list of the expected number of bytes (by the USB) for all binary commands

Command	Bytes	Command	Bytes	Command	Bytes
0x80	1	0x93	5	0xA6	3
0x81	4	0x94	6	0xA7	2
0x82	1	0x95	7	0xA8	4
0x83	1	0x96	8	0xA9	3
0x84	1	0x97	4	0xAA	1
0x85	3	0x98	5	0xAB	1
0x86	2	0x99	7	0xAC	1
0x87	2	0x9A	11 dec	0xAD	5
0x88	3	0x9B	2	0xAE	6
0x89	1	0x9C	2	0xAF	6
0x8A	2	0x9D	3	0xB0	5
0x8B	1	0x9E	1	0xB1	2
0x8C	1	0x9F	1	0xB2	1
0x8D	4	0xA0	4	0xB3	1
0x8E	20 dec	0xA1	3	0xB4	1
0x8F	3	0xA2	5	0xB5	1
0x90	18 dec	0xA3	4	0xB6	1
0x91	18 dec	0xA4	5	0xB7	1
0x92	10 dec	0xA5	6	0xB8	1

Unsupported commands

The following commands are completely unsupported by the current version of the USB board. The USB board will buffer the expected number of bytes (1 byte for unsupported commands) then return ASCII '0' indicating the command is not supported.

0x81 -> 0x8B

0x8D -> 0x9B

0x9D

0xA3

0xA4

0xA5

0xAB

0xAC

0XB3 -> 0XBF

Description of command formats used with NCE RS232 and USB interfaces

	The RS-232 port binary comm in a computer friendly mode		gned to work
	Command format is: <cmd nu<="" td=""><td>mber> <data></data></td><td><data></data></td></cmd>	mber> <data></data>	<data></data>
	Commands range from 0x80 to	0xBF	
NOT			
NOT	E: For commands 0x9F,0xA0,0x byte of 0 will be returne		
	'1'= lo '2'= ca '3'= CV '4'= by '!'= co	b address or address or d te count out mmand complet	l address out of rang op code out of range ata out of range of range ed successfully
******	**********	******	******
	DESCRIPTION	# OF BYTES RETURNED	
0×80	NOP, dummy instruction	(1)	
	y assign loco		!,1,2
	read clock		
0x83	Clock stop	(1)	1
0x84	Clock start	(1)	
0x85 xx xx	Set clock hr/min	(1)	
0x86 xx	Set clock 12/24 0=12 hr 1=24 hr	(1)	!,3
0x87 xx	Set clock ratio	(1)	
0x88 xx xx	Dequeue packet by loco add	r (1)	!,1,2
0x89	Enable main trk, kill prog		!
0x8A yy	Return status of AIU yy		<pre><current byte="" hi=""> <current byte="" lo=""> <change byte="" hi=""> <change byte="" lo=""></change></change></current></current></pre>
0x8B	Kill main trk, enable prog	(1)	
0x8C	Dummy instruction returns followed by CR/LF	"!" (3)	!,0x0D,0x0A
0x8D xxxx mm	Set speed mode of loco xxx to mode mm, 1=14, 2=28, 3=	x (1)	!,1,3
0x8E aaaa nn	<16 data bytes> Write nn bytes, start at a Must have 16 data bytes, p them out to 16 if necessar	(1) aaa ad y	!,4
0x8F aaaa	Read 16 bytes, start at aa	aa (16)	16 bytes
		 b cc (1)	

0.492 cc xx.	;; 0x91 cc xx;	Send 16 char LCD line 4.		SCII char	(1)	!,2	
0.493 ss xx xx xx	;	Send 8 char LCD line 2 r	message to	Cab cc = 8 char	(1)	!,2	
Queue 4 byte packet to TEMP_Q Send ss times 0x95 ss xx xx xx xx xx (1)	,	xx Queue 3 byte	packet to		(1)	!	
Queue 5 byte packet to TEMP_Q Send ss times 0x96 ss xx xx xx xx xx xx xx xx (1)	; 0x94 ss xx xx ;	Queue 4 byte	•	TEMP_Q	(1)	!	
Queue 6 byte packet to TEMP_Q Send ss times ; 0x97 aaaa xx	; 0x95 ss xx xx ;	Queue 5 byte		TEMP_Q	(1)	!	
0x98 aaaa xx xx	; 0x96 ss xx xx	Queue 6 byte		TEMP_Q	(1)	!	
0x98 aaaa xx xx					(1)	!	
Write 2 bytes to aaaa	,				(1)	· · · · · · · · · · · · · · · · · · ·	
Write 4 bytes to aaaa 0x9A aaaa <8 data bytes>	;	Write 2 byte	s to aaaa		. ,		
0x9A aaaa <8 data bytes >	; 0x99 aaaa <4 ;	Write 4 byte			(1)	!	
<pre>(short form of command 0x8A)</pre>	; 0x9A aaaa <8	data bytes>			(1)	1	
0x9C xx	;	(short form	of command	0x8A)		<current byte="" lo=""></current>	
0x9D aaaa Read 1 bytes from aaaa	; 0x9C xx	Execute macr	o number x	X			
0x9E	, ; 0x9D aaaa	Read 1 bytes	from aaaa		(1)	1 byte	
3 = short circuit 0x9F Exit Programming track mode (1) ! = success 0xA0 aaaa xx Program CV aa with data xx in (1) ! = success paged mode 0 = program track no enabled 0xA1 aaaa Read CV aa in paged mode (2) !,0,3 NOTE: cv data followed ! for ok,	,			k mode	(1)	! = success	
0xA0 aaaa xx	;				. ,	3 = short circuit	
<pre></pre>					(1)	! = success	
Read CV aa in paged mode (2) !,0,3 NOTE: cv data followed ! for ok,	; 0xA0 aaaa xx	Program CV a				0 = program track no enabled	
<pre></pre>		Read CV aa i NOTE: cv dat	in paged mo a followed	de ! for ok,	(2)		
Locomotive control command (1) !,1 Sends a speed or function packet to a locomotive. Command Format: 0xA2 <addr_h> <addr_l> <op_l> <data_l> Addr_h and Addr_l are the loco address in DCC format. If a long address is in use, bits 6 and 7 of the high byte are set. Ex: Long address 3 = 0xc0 0x03 Short address 3 = 0x00 0x03 op_l data_l Operation description op_l data_l Operation description address 3 = 0x00 0x03 cop_l data_l Operation description cop_l</data_l></op_l></addr_l></addr_h>	; ;						
Command Format: 0xA2 <addr_h> <addr_l> <op_l> <data_l> Addr_h and Addr_l are the loco address in DCC format. If a long address is in use, bits 6 and 7 of the high byte are set. Ex: Long address 3 = 0xc0 0x03 Short address 3 = 0x00 0x03 op_l data_l Operation description op_l data_l Operation description number of the high byte are set. Ex: Long address 3 = 0x00 0x03 Reverse 28 speed command op_l data_l Operation description number op_l</data_l></op_l></addr_l></addr_h>	;	•	control co	mmand	(1)	!,1	
If a long address is in use, bits 6 and 7 of the high byte are set. Ex: Long address 3 = 0xc0 0x03 Short address 3 = 0x00 0x03 op_1 data_1 Operation description op_1 data_1 Operation description number of the high byte are set. Reverse 28 speed command pop_1 data_1 Operation description number of the high byte are set. Reverse 28 speed command pop_1 data_1 Operation description number of the high byte are set. Reverse 28 speed command pop_1 data_1 Operation description number of the high byte are set. Reverse 28 speed command pop_1 data_1 Operation description number of the high byte are set. Reverse 28 speed command pop_1 data_1 Operation description number of the high byte are set. Reverse 28 speed command pop_2 description number of the high byte are set. Reverse 28 speed command pop_3 description number of the high byte are set. Reverse 28 speed command pop_4 description number of the high byte are set. Reverse 28 speed command pop_4 description number of the high byte are set. number of the high byte are s	; Sends a speed or function packet to a locomotive.						
Ex: Long address 3 = 0xc0 0x03 Short address 3 = 0x00 0x03 cop_1 data_1 Operation description op_1 data_1 Operation description number of the property of	;						
<pre> ; 01 0-7f Reverse 28 speed command ; 02 0-7f Forward 28 speed command ; 03 0-7f Reverse 128 speed command ; 04 0-7f Forward 128 speed command ; 05 0 Estop reverse command ; 06 0 Estop forward command ; 07 0-1f Function group 1, bits 0-3 = F1-F4, bit 4=F0 ; 08 0-0f Function group 2, bits 0-3 = F5-F8 ; 09 0-0f Function group 3, bits 0-3 = F9-F12 </pre>	;	Ex: Long	address	$3 = 0 \times 0 \times 0$	x03	7 or the High byte are set.	
<pre> ; 01 0-7f Reverse 28 speed command ; 02 0-7f Forward 28 speed command ; 03 0-7f Reverse 128 speed command ; 04 0-7f Forward 128 speed command ; 05 0 Estop reverse command ; 06 0 Estop forward command ; 07 0-1f Function group 1, bits 0-3 = F1-F4, bit 4=F0 ; 08 0-0f Function group 2, bits 0-3 = F5-F8 ; 09 0-0f Function group 3, bits 0-3 = F9-F12 </pre>	;	on 1	data 1	Operation	descript	tion	
<pre></pre>	<u>;</u>		_				
<pre> ;</pre>	, ;				•		
<pre></pre>			0-7f	Reverse 12	28 speed	command	
<pre></pre>	;		·				
 97 0-1f Function group 1, bits 0-3 = F1-F4, bit 4=F0 98 0-0f Function group 2, bits 0-3 = F5-F8 99 0-0f Function group 3, bits 0-3 = F9-F12 	;			•			
; 09 0-0f Function group 3, bits 0-3 = F9-F12	;						
			_				
	;						

```
0b
                         0-7f
                                  Set forward consist address for lead loco
               0с
                         0-7f
                                  Set reverse consist address for rear loco
               ρd
                         0-7f
                                  Set forward consist address for rear loco
               0e
                         0-7f
                                  Set reverse consist address for additional loco
                         0-7f Set forward consist address for additional loco
               0f
                       0
               10
                                Del loco from consist
                       0
                                 Kill consist
               11
                       0-9 Set momentum
0-7f No action, always returns success
               12
               13
                        0-7f No action, always returns success
               14
                        0-ff
               15
                                  Functions 13-20 control (bit 0=F13, bit 7=F20)
                         0-ff
                                  Functions 21-28 control (bit 0=F21, bit 7=F28)
               16
               17-7f
                         reserved reserved
; 0xA3 xx xx Queue 3 byte packet to TRK_Q (1) !,1
             (replaces any packet with same
             address if it exists)
; 0xA4 xx xx... Queue 4 byte packet to TRK_Q (1) !,1
              (replaces any packet with same
             address if it exists)
; 0xA5 xx xx... Queue 5 byte packet to TRK_Q (1) !,1
         (replaces any packet with same address if it exists)
 0xA6 rr xx Program register rr with data xx (1) ! = success
            in register mode
                                                 0 = program track no enabled
 0xA7 rr Read register rr in register mode(2) !,3 NOTE: cv data followed ! for ok, 0 = p
                                                 0 = program track no enabled
             Oxff followed by 3 for can't read
; 0xA8 aaaa xx Program CV aaaa with data xx (1) ! = success
in direct mode 0 = program track no enabled
 0xA9 aaaa Read CV aaaa in direct mode (2) !,3 NOTE: cv data followed ! for ok, 0 = program track no enabled
             Oxff followed by 3 for can't read
.
; 0xAA Return software revision number (3) <data1>,<data2>,<data3>; FORMAT: VV.MM.mm
      Perform a soft reset of command (0) Returns nothing
             station (like cycling the power)
;------
; 0xAC Perform a hard reset of command (0) Returns nothing
             station (reset to factory defaults)
; 0xAD <4 data bytes>
              Accy/signal and macro commands (1) !,1
              Command Format: 0xAD <addr_h> <addr_l> <op_1> <data_1>
              Addr h and Addr l are the accessory/signal address (NOT in DCC format).
               Ex: Accessory Address 513 = 0x02 0x01 (hi byte first)
              NOTE: accy/signal address 0 is not a valid address
               0p_1
                      Data_1
                                 Operation description
               01
                         0-255
                                 NCE macro number 0-255
                        0-255 Duplicate of Op_1 command
               02
                        0
               03
                                Accessory Normal direction (ON)
              04
                               Accessory Reverse direction (OFF)
                        0
                        0-1f
               05
                                 Signal Aspect 0-31
               05-7f
                        reserved reserved
```

```
; 0xAE <5 data bytes>
 ***USB COMMAND ONLY***
              OPs program loco CV
                                               (1) !,0,1,3
              Command Format: 0xA2 <addr_h> <addr_l> <CV_h> <CV_l> <data>
              addr_h,addr_l are loco address (same as 0xA2 command)
              CV_h, CV_l are cv address high byte first
             data is 8 bit data for CV
; 0xAF <5 data bytes>
 ***USB COMMAND ONLY***
              OPs program accessory/signal
                                           (1)
                                                     !,0,1,3
              Command Format: 0xA2 <addr_h> <addr_l> <CV_h> <CV_l> <data>
              addr_h,addr_1 are accy/sig address (same as 0xAD command)
              CV_h, CV_l are CV address high byte first
             data is 8 bit data for CV
; 0xB0 <4 data bytes> Reserved for future PowerCab use (1) 0=not supported
 ***USB COMMAND ONLY***
                                                    !=success
; 0xB1 xx
                                              (1) 0=not supported
; ***USB COMMAND ONLY***
                                                    !=success
              SET cab bus address of USB board to xx
              Command Format: 0xB1 <data>
 ______
; 0xB2 xx
                                             (1) 0=not supported
              Enable/disable echo of binary command
                                                    !=success
              to RS-232 port. This command is used
              when AIU broadcast is enabled so computer
              can distinguish between command response
              or AIU broadcast
              Command Format: 0xB2 <data>
              0=no echo, 1=echo 1st byte of command, 2=echo entire command
```

Device Warranty

This device is fully factory tested and warranted against manufacturing defects for a period of 1 year. As the circumstances under which it is installed can not be controlled, failure of the device due to installation problems can not be warranted. This includes misuse, miswiring,or operation under loads beyond the design range of the device. For warranty or non-warranty replacement send the dece (and any payment, if required) to:

NCE Warranty Center 82 East Main St. Webster, New York 14580



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